

ABSTRACT OF THE DISCLOSURE

A method of programming a controller for a movable barrier operator includes enabling and disabling an input device within a predetermined period of time, a
5 predetermined number of times. This sequence of short activations of an input device, such as a switch on a wall unit, puts the controller in a learn mode or a programmed state. Thereafter, the controller is responsive to learn any of the various routines that can
10 be programmed for the movable barrier operator, such as transmitter code, limits of travel, force settings, and so on.